probabilities), although the logistic function can

φ has a value of 0 when there is no association between the two values, that is, when the probability of selecting a value of *A* is constant for any value of *B*.

2. **In n n I**nterdependix 1 we prove that Cramér's $\phi(A, B)$ ϕ measures the linear interpolation from flat to identity matrix (see Figure 1 for the idea). We can therefore refer to φ as the best estimate of the population **n interdependent probability i i p** $p(a \leftrightarrow b)$. This intercorrelation is robust, i.e. it 'gracefully decays' the further it deviates from this ideal. φ is

$$
dp_R(A, b) \equiv - \sum_{i=1}^k a_i b
$$

We note the following.

- 1. Relative dependency $dp_R(B, A)$ is linear with *x* when $p(a)$ is even.
- 2. Measures are ordered in size: $C_{adj} > dp_R(B, A) > \phi > dp_R(A, B)$.
- 3. *dp_R*(*A, B*) (and therefore ϕ) converges to *dp_R*(*B, A*) as *p*(*b*) becomes more even (tends to 1/*k*).

Whereas dp_R measures the distance on the first parameter from the prior (and is thus directional when a prior skew is applied to one variable only), φ is based on the root mean square distance of both variables. C_{adi} appears to behave rather differently to φ, as the right hand graph in Figure 2 shows. Given that the only other bi-directional measure, φ, measures the interdependence of *A* and *B*, there appears to be little advantage in adopting the less conservative *Cadj*.

Finally, for $k = 2$ the following equation also holds:

4. $\phi^2 = dp_R(A, B) \times dp_R(B, A).$

We find an equality between a classical Bayesian approach to dependency and a stochastic approach based on Pearson's χ^2 for one degree of freedom. The proof is given in Appendix 3.

This raises the following question: what does 'directionality' mean here?

Note that *dpR*

6. A worked example

Figure 3 provides a demonstration of plotting confidence intervals on φ

Appendix 1. The best estimate of population interdependent probability is Cramér's φ

Cramér's φ is not merely a 'measure of association'. It repres

Appendix 2. Deriving 2 × 2 rule dependency

For a 2×2 table with a single degree of freedom, the following axioms hold.

A1.
$$
p(a_2) = p(\neg a_1) = 1 - p(a_1); p(a_2 | b_i) = p(\neg a_1 | b_i) = 1 - p(a_1 | b_i),
$$

A2.
$$
p(a_1 | b_i) - p(a_1) = p(a_2) - p(a_2 | b_i)
$$
,

A3.
$$
[p(a_1 | b_i) < p(a_1)] \leftrightarrow [p(a_2) < p(a_2 | b_i)].
$$

A1 is a consequence of the Boolean definition of *A*, A2 can be demonstrated using Bayes' Theorem and A3 is a consequence of A2. A2 further entails that row sums are equal, i.e. $dp_R(a_1, B) =$ $dp_R(a_2, B)$.

Equation (5) may therefore be simplified as follows

$$
dp_R(A, B) = \frac{1}{k} \int_{i=1}^{k} dp_R(a_i, b_j) \times p(b_j) = \int_{j=1}^{k} dp_R(a_i, b_j) \times p(b_j)
$$

=
$$
\frac{p(a_1 | b_1) - p(a_1)}{1 - p(a_1)} \times p(b_1) + \frac{p(a_1) - p(a_1 | b_2)}{p(a_1)} \times p(b_2).
$$

Applying Bayes' Theorem $(p(a_1 | b_2) \equiv p(b_2 | a_1) \times p(a_1) / p(b_2))$ and axiom A1:

$$
dp_R(A, B) = \frac{p(a_1 | b_1)p(b_1)}{1 - p(a_1)} - \frac{p(a_1)p(b_1)}{1 - p(a_1)} + \frac{p(a_1 | b_1)p(b_1)}{p(a_1)} - p(b_1).
$$

The first and third terms then simplify to $[p(a_1 | b_1)p(b_1)] / [(1 - p(a_1))p(a_1)]$, so

$$
dp_R(A, B) = \frac{p(a_1 | b_1)p(b_1) - p(a_1)^2 p(b_1) - (1 - p(a_1))p(a_1)p(b_1)}{(1 - p(a_1))p(a_1)}
$$

$$
= \frac{[p(a_1 | b_1) - p(a_1)]p(b_1)}{p\overline{b}p\overline{a}p\overline{b}q\overline{b}p\overline{c}p(a_1)]p(a_1)}.
$$

Appendix 3. For a 2 × 2 table, $\phi^2 \equiv dp_R(A, B) \times dp_R(B, A)$

The proof is in three stages.

S

STAGE 2. Converting to a+b+c+d notation.

The 2 \times 2 χ^2 statistic, and thus ϕ , may be represented simply in terms of four frequencies in the table, a, b, c and d (note roman font to distinguish from *a*, *a*1, etc). The table is labelled thus, and *N* \equiv a+b+c+d:

$$
\begin{array}{|c|c|c|c|c|} \hline & b_1 & b_2 & \Sigma \\ \hline a & & & \end{array}
$$